

Princeton University
COS 217: Introduction to Programming Systems
Spring 2004 Final Exam Answers

Question 1 (a)

A typical instruction consists of an opcode, a source operand, and a destination operand. The execution steps are: fetch instruction, fetch operands, execute the operation, write results, and increment program counter (or instruction pointer).

Question 1 (b)

The operating system creates a process with virtual memory, loads various sections (text, data, bss, etc) of a program into the virtual memory, jumps to the starting instruction of the program, and destroys the process on the exit of the program.

Question 1 (c)

Exceptions are program errors. Examples are faults, and traps. Interrupts are events generated by hardware. Examples are keyboard inputs, and disk I/O operation completion.

Question 1 (d)

A procedure call runs in user mode, whereas a system call looks like a procedure call, but runs in kernel mode.

The typical calling sequence of a procedure call is:

Caller:

- Push arguments onto the stack.
- Call the procedure (including pushing the return address on the stack).
- Get return results (typically from a register).

Callee:

- Setup the stack frame (including local variables).
- Execute the procedure with the arguments and local variables in the stack frame.
- Pop off the stack frame.
- Return to caller (using the saved return address on the stack).

The typical calling sequence of a system call is:

Caller:

- Move arguments to registers or push arguments onto the stack.
- Trap instruction with a system call number.
- Get return results (typically from a register and error code is in a agreed variable).

Callee (in the OS kernel):

The system call mechanism switches the call to the called system call code.

- Setup the stack frame (may need to copy arguments to kernel stack).
- Execute the system call with the arguments.
- Pop off the stack frame.
- Return to caller using a special mode switch instruction (such as IRET).

Question 2

```
=====
# sum.s
=====

=====
.section ".text"
=====
```

```

-----  

# int sum(int x, int y)  

#  

# Return the sum of all the numbers between 1 and y that are divisible  

# by x. x and y are positive.  

#  

# Formal parameter offsets:  

.equ X, 8  

.equ Y, 12  

# Local variable offsets:  

.equ I, -4  

.equ ISUM, -8  

-----  

.globl sum  

.type sum,@function  

sum:  

    pushl %ebp  

    movl %esp, %ebp  

    # int i = 1;  

    pushl $1  

    # int iSum = 0;  

    pushl $0  

loop:  

    # if (i > y) goto endloop;  

    movl I(%ebp), %eax  

    cmpl Y(%ebp), %eax  

    jg endloop  

    # if ((i % x) != 0) goto endif;  

    movl I(%ebp), %eax  

    movl $0, %edx  

    idivl X(%ebp)  

    cmpl $0, %edx  

    jne endif  

    # iSum += i;  

    movl I(%ebp), %eax  

    addl %eax, ISUM(%ebp)  

endif:  

    # i++;  

    incl I(%ebp)  

    # goto loop;  

    jmp loop  

endloop:  

    # return iSum;  

    movl ISUM(%ebp), %eax  

    movl %ebp, %esp  

    popl %ebp  

    ret

```

Question 3 (a)

```

#include <stdio.h>

#define ESCAPE_CHAR 0377

enum State {START_STATE, ONE_IN_A_ROW_STATE, TWO_IN_A_ROW_STATE,
    COMPRESS_STATE};

```

```

int main(void)
{
    int iChar;
    int iPrevChar;
    int iCount;
    enum State iState = START_STATE;

    for (;;)
    {
        iChar = getchar();

        switch (iState)
        {
            case START_STATE:
                if (iChar == EOF)
                {
                    return 0;
                }
                else if (iChar == ESCAPE_CHAR)
                {
                    iPrevChar = iChar;
                    iCount = 1;
                    iState = COMPRESS_STATE;
                }
                else
                {
                    iPrevChar = iChar;
                    iState = ONE_IN_A_ROW_STATE;
                }
                break;

            case ONE_IN_A_ROW_STATE:
                if (iChar == EOF)
                {
                    putchar(iPrevChar);
                    return 0;
                }
                else if (iChar != iPrevChar)
                {
                    putchar(iPrevChar);
                    iPrevChar = iChar;
                    if (iChar == ESCAPE_CHAR)
                    {
                        iCount = 1;
                        iState = COMPRESS_STATE;
                    }
                    else
                        iState = ONE_IN_A_ROW_STATE;
                }
                else
                {
                    iState = TWO_IN_A_ROW_STATE;
                }
                break;

            case TWO_IN_A_ROW_STATE:
                if (iChar == EOF)
                {
                    putchar(iPrevChar);
                    putchar(iPrevChar);
                    return 0;
                }
                else if (iChar != iPrevChar)
                {
                    putchar(iPrevChar);
                    putchar(iPrevChar);
                    iPrevChar = iChar;
                    if (iChar == ESCAPE_CHAR)
                    {
                        iCount = 1;
                        iState = COMPRESS_STATE;
                    }
                    else
                }
        }
    }
}

```

```

        iState = ONE_IN_A_ROW_STATE;
    }
    else
    {
        iCount = 3;
        iState = COMPRESS_STATE;
    }
    break;

case COMPRESS_STATE:
    if (iChar == EOF)
    {
        putchar(ESCAPE_CHAR);
        putchar(iPrevChar);
        putchar(iCount);
        return 0;
    }
    else if (iChar != iPrevChar)
    {
        putchar(ESCAPE_CHAR);
        putchar(iPrevChar);
        putchar(iCount);
        iPrevChar = iChar;
        if (iChar == ESCAPE_CHAR)
        {
            iCount = 1;
            iState = COMPRESS_STATE;
        }
        else
            iState = ONE_IN_A_ROW_STATE;
    }
    else
    {
        iCount++;
        if (iCount == 255)
        {
            putchar(ESCAPE_CHAR);
            putchar(iPrevChar);
            putchar(iCount);
            iState = START_STATE;
        }
        else
            iState = COMPRESS_STATE;
    }
    break;
}
}

return 0;
}

```

Question 3 (b)

```

#include <stdio.h>

#define ESCAPE_CHAR 0377

int main(void)
{
    int i;
    int iChar;
    int iCount;

    while ((iChar = getchar()) != EOF)
    {
        if (iChar == ESCAPE_CHAR)
        {
            iChar = getchar();
            iCount = getchar();
            for (i = 0; i < iCount; i++)
                putchar(iChar);
        }
    }
}

```

```

        else
            putchar(iChar);
    }

    return 0;
}

```

Question 3 (c)

Produce output that is known to be right or wrong:

- Compress file X to produce file Y. Manually examine Y. Decompress file Y to produce file Z. Use diff to compare X and Z; they should be identical. Repeat for various X...

Boundary condition tests:

- X contains 0, 1, 2, 3, 4 characters, with no consecutive characters the same.
- X contains 1, 2, 3, 4, 254, 255, 256 characters, all of which are 0377.
- X contains 1, 2, 3, 4, 254, 255, 256 characters, all of which are the same.
- X contains only pairs of characters.
- X contains only triplets of characters.

Stress tests:

- X contains a large number of random characters.
- X contains a large number of characters, all of which are 0377.
- X contains a large number of characters, all of which are the same.
- X contains a large number of characters, with no consecutive characters the same.
- X contains a large number of characters, all of which occur in pairs.
- X contains a large number of characters, all of which occur in triplets.

Logical path tests:

- X contains a random number of random characters.

Question 4 (a)

```

#include <stdio.h>
#include <stdlib.h>
#include <unistd.h>
#include <sys/types.h>
#include <sys/wait.h>

int main(int argc, char *argv[])
{
    int piPipeFd[2];
    int iProducerPid;
    int iConsumerPid;
    int iRet;

    iRet = pipe(piPipeFd);
    if (iRet == -1) {perror(argv[0]); return 1; }

    ffflush(NULL);
    iProducerPid = fork();
    if (iProducerPid == -1) {perror(argv[0]); return 1; }

    if (iProducerPid == 0)
    {
        char *ppcArgv[3] = {"ls", "-l", NULL};

        iRet = close(piPipeFd[0]);
        if (iRet == -1) {perror(argv[0]); exit(1); }
        iRet = close(1);
        if (iRet == -1) {perror(argv[0]); exit(1); }
        iRet = dup(piPipeFd[1]);
        if (iRet == -1) {perror(argv[0]); exit(1); }
        iRet = close(piPipeFd[1]);
        if (iRet == -1) {perror(argv[0]); exit(1); }
    }
}

```

```

execvp(ppcArgv[0], ppcArgv);
perror(argv[0]);
exit(1);
}

fflush(NULL);
iConsumerPid = fork();
if (iConsumerPid == -1) {wait(NULL); perror(argv[0]); return 1; }

if (iConsumerPid == 0)
{
    char *ppcArgv[2] = {"more", NULL};

    iRet = close(piPipeFd[1]);
    if (iRet == -1) {perror(argv[0]); exit(1); }
    iRet = close(0);
    if (iRet == -1) {perror(argv[0]); exit(1); }
    iRet = dup(piPipeFd[0]);
    if (iRet == -1) {perror(argv[0]); exit(1); }
    iRet = close(piPipeFd[0]);
    if (iRet == -1) {perror(argv[0]); exit(1); }

    execvp(ppcArgv[0], ppcArgv);
    perror(argv[0]);
    exit(1);
}

iRet = close(piPipeFd[0]);
if (iRet == -1) {wait(NULL); wait(NULL); perror(argv[0]); return 1; }
iRet = close(piPipeFd[1]);
if (iRet == -1) {wait(NULL); wait(NULL); perror(argv[0]); return 1; }

wait(NULL);
wait(NULL);

return 0;
}

```

Question 4 (b)

Add the statement

```
alarm(360);
```

immediately prior to the call to execvp that executes the "more" program.

Explanation:

- The program must measure wall-clock time, not CPU time. So the program must create an alarm, not an interval timer.
- Alarms are not preserved across a fork. So the alarm must be created within the child process, not within the parent process.
- Alarms are preserved across an exec. So an alarm created in the second child process will be inherited by the "more" program.
- Registration of a user-defined signal handler is not preserved across an exec. So there is no reason to register a user-defined signal handler in the second child process.
- The default handler for the SIGALRM signal causes process exit. Since that is the desired behavior, there is no need to register a user-defined signal handler.

Question 5 (a)

```

#include <stdio.h>
#include <assert.h>
#include <stdlib.h>
#define N 10000

int MakeData( int x[], float y[], int size )
{
    int c;
    int i;

```

```

for ( i = 0; i < N && ((c = getchar()) != EOF); i++)
    x[i] = c;
size = i;
i = 0;
while ( i < size )
{
    y[i] = (float) x[i] + i;
    i++;
}
return size;
}

int main(void)
{
    int size;
    int *iBuf;
    float *fBuf;
    iBuf = (int *) malloc(sizeof(int) * N);
    fBuf = (float *) malloc(sizeof(float) * N);
    size = MakeData( iBuf, fBuf, N );
    fwrite( fBuf, sizeof(float), size, stdout );
    return 0;
}

```

Question 5 (b)

```

#include <stdio.h>
#include <assert.h>
#include <stdlib.h>
#define N 10000

int MakeData( int x[], float y[], int size )
{
    int c;
    int i;
    assert( x != NULL );
    assert( y != NULL );
    for ( i = 0; i < N && ((c = getchar()) != EOF); i++)
        x[i] = c;
    size = i;
    i = 0;
    while ( i < size )
    {
        y[i] = (float) x[i] + i;
        i++;
    }
    return size;
}

int main(void)
{
    int size;
    int *iBuf;
    float *fBuf;
    size_t uiRet;
    iBuf = (int *) malloc(sizeof(int) * N);
    assert( iBuf != NULL );
    fBuf = (float *) malloc(sizeof(float) * N);
    assert( fBuf != NULL );
    size = MakeData( iBuf, fBuf, N );
    uiRet = fwrite( fBuf, sizeof(float), size, stdout );
    assert( uiRet == size );
    return 0;
}

```