

Assembly Language: IA-32 Instructions

Goals of this Lecture

- Help you learn how to:
 - Manipulate data of various sizes
 - Leverage more sophisticated addressing modes
 - Use condition codes and jumps to change control flow
 - ... and thereby ...
 - Write more efficient assembly-language programs
 - Understand the relationship to data types and common programming constructs in high-level languages
- Focus is on the assembly-language code
 - Rather than the layout of memory for storing data

Variable Sizes in High-Level Language

- C data types vary in size
 - Character: 1 byte
 - Short, int, and long: varies, depending on the computer
 - Float and double: varies, depending on the computer
 - Pointers: typically 4 bytes
- Programmer-created types
 - Struct: arbitrary size, depending on the fields
- Arrays
 - Multiple consecutive elements of some fixed size
 - Where each element could be a struct

Supporting Different Sizes in IA-32

- Three main data sizes
 - Byte (b): 1 byte
 - Word (w): 2 bytes
 - Long (l): 4 bytes
- Separate assembly-language instructions
 - E.g., `addb`, `addw`, and `addl`
- Separate ways to access (parts of) a register
 - E.g., `%ah` or `%al`, `%ax`, and `%eax`
- Larger sizes (e.g., struct)
 - Manipulated in smaller byte, word, or long units

Byte Order in Multi-Byte Entities

- Intel is a **little endian** architecture

- Least significant byte of multi-byte entity is stored at lowest memory address

- “Little end goes first”

The int 5 at address 1000:

1000	00000101
1001	00000000
1002	00000000
1003	00000000

- Some other systems use **big endian**

- Most significant byte of multi-byte entity is stored at lowest memory address

- “Big end goes first”

The int 5 at address 1000:

1000	00000000
1001	00000000
1002	00000000
1003	00000101

Little Endian Example

```
int main(void) {  
    int i=0x003377ff, j;  
    unsigned char *p = (unsigned char *) &i;  
    for (j=0; j<4; j++)  
        printf("Byte %d: %x\n", j, p[j]);  
}
```

Output on a
little-endian
machine

Byte 0: ff
Byte 1: 77
Byte 2: 33
Byte 3: 0

IA-32 General Purpose Registers

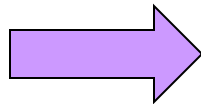
31	15	8	7	0	16-bit	32-bit
	AH		AL		AX	EAX
	BH		BL		BX	EBX
	CH		CL		CX	ECX
	DH		DL		DX	EDX
	SI					ESI
	DI					EDI

General-purpose registers

C Example: One-Byte Data

Global *char* variable *i* is in *%al*,
the *lower byte* of the “A” register.

```
char i;  
...  
if (i > 5)  
{  
    i++;  
}  
else  
    i--;  
}
```

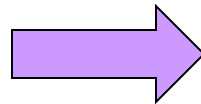


```
    cmpb $5, %al  
    jle else  
    incb %al  
    jmp endif  
else:  
    decb %al  
endif:
```


C Example: Four-Byte Data

Global *int* variable *i* is in *%eax*,
the *full 32 bits* of the “A” register.

```
int i;  
...  
if (i > 5)  
{  
    i++;  
}  
else  
    i--;  
}
```



```
    cmpl $5, %eax  
    jle else  
    incl %eax  
    jmp endif  
else:  
    decl %eax  
endif:
```

Loading and Storing Data

- Processors have many ways to access data
 - Known as “addressing modes”
 - Two simple ways seen in previous examples
- Immediate addressing
 - Example: `movl $0, %ecx`
 - Data (e.g., number “0”) embedded in the instruction
 - Initialize register ECX with zero
- Register addressing
 - Example: `movl %edx, %ecx`
 - Choice of register(s) embedded in the instruction
 - Copy value in register EDX into register ECX

Accessing Memory

- Variables are stored in memory
 - Global and static local variables in Data or BSS section
 - Dynamically allocated variables in the heap
 - Function parameters and local variables on the stack
- Need to be able to load from and store to memory
 - To manipulate the data directly in memory
 - Or copy the data between main memory and registers
- IA-32 has many different addressing modes
 - Corresponding to common programming constructs
 - E.g., accessing a global variable, dereferencing a pointer, accessing a field in a struct, or indexing an array

Direct Addressing

- Load or store from a particular memory location
 - Memory address is embedded in the instruction
 - Instruction reads from or writes to that address
- IA-32 example: `movl 2000, %ecx`
 - Four-byte variable located at address 2000
 - Read four bytes starting at address 2000
 - Load the value into the ECX register
- Useful when the address is known in advance
 - Global variables in the Data or BSS sections
- Can use a label for (human) readability
 - E.g., "i" to allow "movl i, %eax"

Indirect Addressing

- Load or store from a previously-computed address
 - Register with the address is embedded in the instruction
 - Instruction reads from or writes to that address
- IA-32 example: `movl (%eax), %ecx`
 - EAX register stores a 32-bit address (e.g., 2000)
 - Read long-word variable stored at that address
 - Load the value into the ECX register
- Useful when address is not known in advance
 - Dynamically allocated data referenced by a pointer
 - The “(%eax)” essentially dereferences a pointer

Base Pointer Addressing

- Load or store with an offset from a base address
 - Register storing the base address
 - Fixed offset also embedded in the instruction
 - Instruction computes the address and does access
- IA-32 example: `movl 8(%eax), %ecx`
 - EAX register stores a 32-bit base address (e.g., 2000)
 - Offset of 8 is added to compute address (e.g., 2008)
 - Read long-word variable stored at that address
 - Load the value into the ECX register
- Useful when accessing part of a larger variable
 - Specific field within a "struct"
 - E.g., if "age" starts at the 8th byte of "student" record

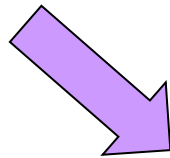
Indexed Addressing

- Load or store with an offset and multiplier
 - Fixed based address embedded in the instruction
 - Offset computed by multiplying register with constant
 - Instruction computes the address and does access
- IA-32 example: `movl 2000(%eax,4), %ecx`
 - Index register EAX (say, with value of 10)
 - Multiplied by a multiplier of 1, 2, 4, or 8 (say, 4)
 - Added to a fixed base of 2000 (say, to get 2040)
- Useful to iterate through an array (e.g., `a[i]`)
 - Base is the start of the array (i.e., "a")
 - Register is the index (i.e., "i")
 - Multiplier is the size of the element (e.g., 4 for "int")

Indexed Addressing Example

```
int a[20];  
  
int i, sum=0;  
for (i=0; i<20; i++)  
    sum += a[i];
```

← global variable



EAX: i
EBX: sum
ECX: temporary

```
movl $0, %eax  
movl $0, %ebx  
sumloop:  
movl a(,%eax,4), %ecx  
addl %ecx, %ebx  
incl %eax  
cmpl $19, %eax  
jle sumloop
```


Effective Address: More Generally

$$\text{Offset} = \left(\begin{array}{c} \text{eax} \\ \text{ebx} \\ \text{ecx} \\ \text{edx} \\ \text{esp} \\ \text{ebp} \\ \text{esi} \\ \text{edi} \end{array} \right) + \left(\begin{array}{c} \text{eax} \\ \text{ebx} \\ \text{ecx} \\ \text{edx} \\ \text{esp} \\ \text{ebp} \\ \text{esi} \\ \text{edi} \end{array} \right) * \left(\begin{array}{c} 1 \\ 2 \\ 4 \\ 8 \end{array} \right) + \left(\begin{array}{c} \text{None} \\ 8\text{-bit} \\ 16\text{-bit} \\ 32\text{-bit} \end{array} \right)$$

Base
Index
scale
displacement

- Displacement `movl foo, %ebx`
- Base `movl (%eax), %ebx`
- Base + displacement `movl foo(%eax), %ebx`
`movl 1(%eax), %ebx`
- (Index * scale) + displacement `movl (,%eax,4), %ebx`
- Base + (index * scale) + displacement `movl foo(%edx,%eax,4), %ebx`

Data Access Methods: Summary

- **Immediate addressing:** data stored in the instruction itself
 - `movl $10, %ecx`
- **Register addressing:** data stored in a register
 - `movl %eax, %ecx`
- **Direct addressing:** address stored in instruction
 - `movl foo, %ecx`
- **Indirect addressing:** address stored in a register
 - `movl (%eax), %ecx`
- **Base pointer addressing:** includes an offset as well
 - `movl 4(%eax), %ecx`
- **Indexed addressing:** instruction contains base address, and specifies an index register and a multiplier (1, 2, 4, or 8)
 - `movl 2000(,%eax,1), %ecx`

Control Flow

- Common case
 - Execute code sequentially
 - One instruction after another
- Sometimes need to change control flow
 - If-then-else
 - Loops
 - Switch
- Two key ingredients
 - Testing a condition
 - Selecting what to run next based on result

```
    cmpl $5, %eax
    jle else
    incl %eax
    jmp endif
else:
    decl %eax
endif:
```

Condition Codes

- 1-bit registers set by arithmetic & logic instructions
 - ZF: Zero Flag
 - SF: Sign Flag
 - CF: Carry Flag
 - OF: Overflow Flag
- Example: "addl Src, Dest" ("t = a + b")
 - ZF: set if t == 0
 - SF: set if t < 0
 - CF: set if carry out from most significant bit
 - *Unsigned* overflow
 - OF: set if two's complement overflow
 - (a>0 && b>0 && t<0)
|| (a<0 && b<0 && t>=0)

Condition Codes (continued)

- Example: "cmpl Src2,Src1" (compare b,a)
 - Like computing $a-b$ without setting destination
 - ZF: set if $a == b$
 - SF: set if $(a-b) < 0$
 - CF: set if carry out from most significant bit
 - Used for unsigned comparisons
 - OF: set if two's complement overflow
 - $(a > 0 \ \&\& \ b < 0 \ \&\& \ (a-b) < 0) \ || \ (a < 0 \ \&\& \ b > 0 \ \&\& \ (a-b) > 0)$
- Flags are *not* set by lea, inc, or dec instructions

Example Five-Bit Comparisons

- Comparison: `cmp $6, $12`
 - Not zero: `ZF=0` (diff is not 00000)
 - Positive: `SF=0` (first bit is 0)
 - No carry: `CF=0` (unsigned diff is correct)
 - No overflow: `OF=0` (signed diff is correct)

01100		01100
- <u>00110</u>	→	+ <u>11010</u>
??		00110
- Comparison: `cmp $12, $6`
 - Not zero: `ZF=0` (diff is not 00000)
 - Negative: `SF=1` (first bit is 1)
 - Carry: `CF=1` (unsigned diff is wrong)
 - No overflow: `OF=0` (signed diff is correct)

00110		00110
- <u>01100</u>	→	+ <u>10100</u>
??		11010
- Comparison: `cmp $-6, $-12`
 - Not zero: `ZF=0` (diff is not 00000)
 - Negative: `SF=1` (first bit is 1)
 - Carry: `CF=1` (unsigned diff of 20 and 28 is wrong)
 - No overflow: `OF=0` (signed diff is correct)

10100		10100
- <u>11010</u>	→	+ <u>00110</u>
??		11010

Jumps after Comparison (cml)

- Equality
 - Equal: je (ZF)
 - Not equal: jne (\sim ZF)
- Below/above (e.g., unsigned arithmetic)
 - Below: jb (CF)
 - Above or equal: jae (\sim CF)
 - Below or equal: jbe (CF | ZF)
 - Above: ja (\sim (CF | ZF))
- Less/greater (e.g., signed arithmetic)
 - Less: jl ($SF \wedge OF$)
 - Greater or equal: jge (\sim ($SF \wedge OF$))
 - Less or equal: jle (($SF \wedge OF$) | ZF)
 - Greater: jg (!(($SF \wedge OF$) | ZF))

Branch Instructions

- Conditional jump
 - $j\{l,g,e,ne,\dots\}$ target if (condition) {eip = target}

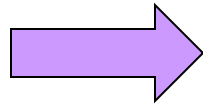
Comparison	Signed	Unsigned	
=	e	e	<i>“equal”</i>
≠	ne	ne	<i>“not equal”</i>
>	g	a	<i>“greater, above”</i>
≥	ge	ae	<i>“...-or-equal”</i>
<	l	b	<i>“less, below”</i>
≤	le	be	<i>“...-or-equal”</i>
overflow/carry	o	c	
no ovf/carry	no	nc	

- Unconditional jump
 - jmp target
 - jmp *register

Jumping

- Simple model of a "goto" statement
 - Go to a particular place in the code
 - Based on whether a condition is true or false
 - Can represent if-the-else, switch, loops, etc.
- Pseudocode example: If-Then-Else

```
if (Test) {  
    then-body;  
} else {  
    else-body;  
}
```

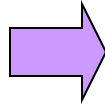


```
if (!Test) jump to Else;  
then-body;  
jump to Done;  
Else:  
    else-body;  
Done:
```

Jumping (continued)

- Pseudocode example: Do-While loop

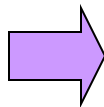
```
do {  
  Body;  
} while (Test);
```



```
loop:  
  Body;  
  if (Test) then jump to loop;
```

- Pseudocode example: While loop

```
while (Test)  
  Body;
```



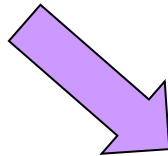
```
  jump to middle;  
loop:  
  Body;  
middle:  
  if (Test) then jump to loop;
```

Jumping (continued)

- Pseudocode example: For loop

```
for (Init; Test; Update)
```

```
    Body
```



```
    Init;  
    if (!Test) jump to done;  
loop:  
    Body;  
    Update;  
    if (Test) jump to loop;  
done:
```

Arithmetic Instructions

- Simple instructions

- `add{b,w,l} source, dest` $dest = source + dest$
- `sub{b,w,l} source, dest` $dest = dest - source$
- `Inc{b,w,l} dest` $dest = dest + 1$
- `dec{b,w,l} dest` $dest = dest - 1$
- `neg{b,w,l} dest` $dest = \sim dest + 1$
- `cmp{b,w,l} source1, source2` $source2 - source1$

- Multiply

- `mul` (unsigned) or `imul` (signed)

`mul %ebx` # `edx, eax = eax * ebx`

- Divide

- `div` (unsigned) or `idiv` (signed)

`idiv %ebx` # `edx, eax / ebx`

- Many more in Intel manual (volume 2)

- `adc`, `sbb`, decimal arithmetic instructions

Bitwise Logic Instructions

- Simple instructions
 - `and{b,w,l} source, dest`
 - `or{b,w,l} source, dest`
 - `xor{b,w,l} source, dest`
 - `not{b,w,l} dest`
 - `sal{b,w,l} source, dest (arithmetic)`
 - `sar{b,w,l} source, dest (arithmetic)`
 - Many more in Intel Manual (volume 2)
 - Logic shift
 - Rotation shift
 - Bit scan
 - Bit test
 - Byte set on conditions
- `dest = source & dest`
`dest = source | dest`
`dest = source ^ dest`
`dest = ~dest`
`dest = dest << source`
`dest = dest >> source`

Data Transfer Instructions

- **mov{b,w,l} source, dest**

- General move instruction

- **push{w,l} source**

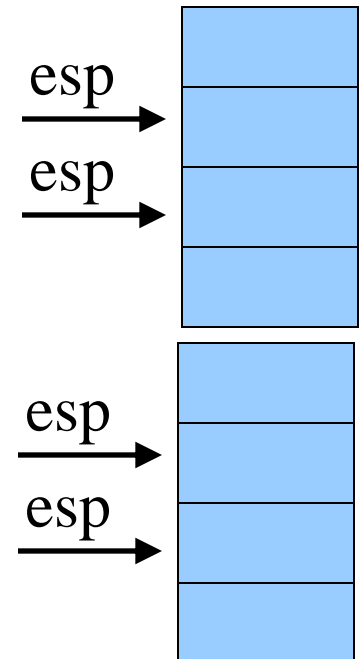
```
pushl %ebx    # equivalent instructions
              subl $4, %esp
              movl %ebx, (%esp)
```

- **pop{w,l} dest**

```
popl %ebx    # equivalent instructions
              movl (%esp), %ebx
              addl $4, %esp
```

- Many more in Intel manual (volume 2)

- Type conversion, conditional move, exchange, compare and exchange, I/O port, string move, etc.



Conclusions

- *Accessing data*
 - Byte, word, and long-word data types
 - Wide variety of addressing modes
- *Control flow*
 - Common *C* control-flow constructs
 - Condition codes and jump instructions
- *Manipulating data*
 - Arithmetic and logic operations
- *Next time*
 - Calling functions, using the stack